

## Author index to volume 9

- Anderson, J.N., see Song, Y.-D. 9 (1992) 271
- Benjamin, D.P., Reformulating path-planning problems by task-preserving abstraction 9 (1992) 105
- Bidaud, P., see Duhaut, D. 9 (1992) 299
- Carroll, R.L., see Geng, Z. 9 (1992) 237
- Donald, B.R. and J. Jennings with contributions from R. Brown, Constructive recognizability for task-directed robot programming 9 (1992) 41
- Dorst, L., Towards formal theories of autonomous goal-directed behavior (Guest Editorial) 9 (1992) 1
- Dorst, L. and H.-L. Wu, The geometry of knowledge acquisition through motion and sensing 9 (1992) 75
- Duhaut, D., P. Bidaud and D. Fontaine, IAda: A language for robot programming based on Ada 9 (1992) 299
- ElMaraghy, H.A. and L. Laperrière, Modelling and sequence generation for robotized mechanical assembly 9 (1992) 137
- Fontaine, D., see Duhaut, D. 9 (1992) 299
- Geng, Z., L.S. Haynes, J.D. Lee and R.L. Carroll, On the dynamic model and kinematic analysis of a class of Stewart platforms 9 (1992) 237
- Gosselin, C.M., The optimum design of robotic manipulators using dexterity indices 9 (1992) 213
- Gosselin, C.M., see Jamshidi, M. 9 (1992) 199
- Haynes, L.S., see Geng, Z. 9 (1992) 237
- Honey, W.E. and M. Jamshidi, ROBO\_SIM: A robotics simulation environment on personal computers 9 (1992) 305
- Hyder, A., see Zsombor-Murray, P.J. 9 (1992) 227
- Jamshidi, M., see Honey, W.E. 9 (1992) 305
- Jamshidi, M., see Liou, J.N. 9 (1992) 283
- Jamshidi, M. and C.M. Gosselin, Trends in robot kinematics, dynamics, control, sensing, programming and simulation (Guest Editorial) 9 (1992) 199
- Jennings, J., see Donald, B.R. 9 (1992) 41
- Kent, E.W. and M.E. Rosar, The submetric formalism for task representation 9 (1992) 115
- Koditschek, D.E., Task encoding: Toward a scientific paradigm for robot planning and control 9 (1992) 5
- Kröse, B.J.A., see Verschure, P.F.M.J. 9 (1992) 181
- Krstulović, A., see Potkonjak, V. 9 (1992) 165
- Krstulović, A., see Potkonjak, V. 9 (1992) 171
- Laperrière, L., see ElMaraghy, H.A. 9 (1992) 137
- Lee, J.D., see Geng, Z. 9 (1992) 237
- Li, B., see Zhuang, H. 9 (1992) 255
- Liou, J.N. and M. Jamshidi, On the robust adaptive control of a contour-following robotic system 9 (1992) 283
- Middleton, R.H., see Song, Y.-D. 9 (1992) 271
- Nair, S.S., R. Singh, K.J. Waldron and V.J. Vohnout, Power system of a multi-legged walking robot 9 (1992) 149
- Oncu, B.A., see Pennock, G.R. 9 (1992) 201
- Pennock, G.R. and B.A. Oncu, Static force analysis of a three-cylindric robot using the theory of screws 9 (1992) 201
- Pfeifer, R., see Verschure, P.F.M.J. 9 (1992) 181
- Potkonjak, V. and A. Krstulović, Mathematical modelling of a redundant anthropomorphic arm (Part I) 9 (1992) 165
- Potkonjak, V. and A. Krstulović, Simulation of a redundant anthropomorphic arm (Part II) 9 (1992) 171

- Rosar, M.E., see Kent, E.W. 9 (1992) 115  
Roth, Z.S., see Zhuang, H. 9 (1992) 255
- Singh, R., see Nair, S.S. 9 (1992) 149  
Song, Y.-D., R.H. Middleton and J.N. Anderson, Study on the exponential path tracking control of robot manipulators via direct adaptive methods 9 (1992) 271
- Verschure, P.F.M.J., B.J.A. Kröse and R. Pfeifer, Distributed adaptive control: The self-organization of structured behavior 9 (1992) 181  
Vohnout, V.J., see Nair, S.S. 9 (1992) 149
- Waldron, K.J., see Nair, S.S. 9 (1992) 149  
Wu, H.-L., see Dorst, L. 9 (1992) 75
- Xie, X., see Zhuang, H. 9 (1992) 255
- Zhuang, H., B. Li, Z.S. Roth and X. Xie, Self-calibration and mirror center offset elimination of a multi-beam laser tracking system 9 (1992) 255  
Zsombor-Murray, P.J. and A. Hyder, An equilateral tetrahedral mechanism 9 (1992) 227

## Subject index to volume 9

Abstraction	9 (1992) 75	Optimization	9 (1992) 213
Ada	9 (1992) 299	Overconstrained	9 (1992) 227
Adaptive control	9 (1992) 271		
Artificial intelligence	9 (1992) 181	Parallel	9 (1992) 227
Assembly sequence planning	9 (1992) 137	Parallel link manipulator	9 (1992) 237
Autonomous agents	9 (1992) 41, 181	Path tracking	9 (1992) 271
Autonomous systems	9 (1992) 115	Perceptual equivalence	9 (1992) 41
		Product model	9 (1992) 137
Bang-bang proportional control	9 (1992) 271	Prolog	9 (1992) 299
Bayesian decision theory	9 (1992) 75		
		Reasoning	9 (1992) 75
Classical conditioning	9 (1992) 181	Recognizability	9 (1992) 41
Computer-aided system design	9 (1992) 305	Redundancy	9 (1992) 165, 171
Computer simulation	9 (1992) 305	Reformulation	9 (1992) 105
Contour-following robotic system	9 (1992) 283	Representation	9 (1992) 75
Coordinate measuring	9 (1992) 255	Representation change	9 (1992) 105
		Robot	9 (1992) 115
Decomposition	9 (1992) 105	Robot calibration	9 (1992) 255
Design	9 (1992) 213	Robot control	9 (1992) 5
Dexterity	9 (1992) 213	Robot dynamics	9 (1992) 237
Dual-Jacobian matrix	9 (1992) 201	Robotic assembly	9 (1992) 137
Dynamical systems theory applied to robotics	9 (1992) 5	Robotics	9 (1992) 41, 201, 271
Dynamics	9 (1992) 171	Robot kinematics	9 (1992) 165, 171, 237
Dynamic simulation	9 (1992) 149	Robot planning	9 (1992) 5
		Robot power system	9 (1992) 149
Emergence	9 (1992) 181	Robot programming	9 (1992) 299
Exponential convergence	9 (1992) 271	Robots	9 (1992) 305
		Robust adaptive control	9 (1992) 283
Industrial robots	9 (1992) 305		
		Screw theory	9 (1992) 201
Kinematics	9 (1992) 213, 227	Self-calibration	9 (1992) 255
Knowledge acquisition	9 (1992) 75	Sensor-based control	9 (1992) 181
Knowledge updating	9 (1992) 75	Simulation	9 (1992) 171
		Software tools	9 (1992) 305
Laser tracking	9 (1992) 255	Static analysis	9 (1992) 201
Laser tracking measuring	9 (1992) 255	Stewart platform	9 (1992) 237
Legged robots	9 (1992) 149	Synergy	9 (1992) 165
		System integration	9 (1992) 149
Macro problem solving	9 (1992) 105		
Manipulator	9 (1992) 213	Task-directed sensing	9 (1992) 41
Mechanism	9 (1992) 227	Task planning	9 (1992) 115
Mirror center offset	9 (1992) 255		
Mobile robots	9 (1992) 41, 181	Uncertainty	9 (1992) 41
Mobility	9 (1992) 227		
Model reference adaptive control	9 (1992) 283	Variable structure control	9 (1992) 283
Models	9 (1992) 41	Vector space geometry	9 (1992) 75
Neuro-computing	9 (1992) 181	Workspace	9 (1992) 227
Numerical analysis	9 (1992) 305		

